Circumscribed DP Polygonal Approximation for Curvilinear Obstacle Representation

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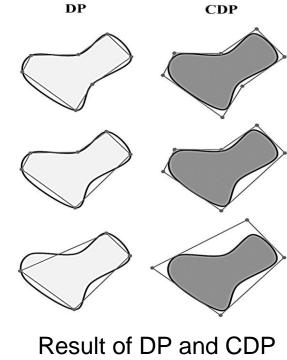
 $\varepsilon(m)$

0.05

0.08

0.11

- DP algorithm does not covered all actual obstacle area and it ignores the outer area.
- Both vector and grid maps can be used in the CDP algorithm.
- Outer Area of result of polygon approximation by CDP algorithm is always 0 (%).
- It can be confirmed that clearance is guaranteed when path planning with ECD method.



Result of DP and CDP
Algorithms according to ε
value